1. (3 pts) What is Amdahl’s law, in words?

2. (3 pts) There are two different ways to measure performance. What are they?

3. (3 pts) Why doesn’t MIPS have a subtract immediate instruction?

4. (3 pts) Are there any MIPS instructions which do not use the ALU? If so, which one(s)?

5. (3 pts) Clock rates have grown by a factor of 1000 while power consumed has only grown by a factor of 30. How was this accomplished?

6. (3 pts) The 32-bit quantity 0x12345678 is going to be stored in memory at location 0x100. If the memory is byte-addressable and uses a little-endian format, what does memory location 0x100 contain after the store occurs?
7. (4 pts) An important program spends 40% of its time doing Floating Point operations, and 30% of its time doing integer arithmetic. By redesigning the hardware you can either make the Floating Point unit twice as fast, or the integer unit 80% faster. Which should you do, and why?

8. (4 pts) Processor A requires 200 instructions to execute a given program, uses 3 cycles per instruction, and has a cycle time of 5 ns. Processor B only requires 2 cycles per instruction, but requires 250 instructions to do the same program. What must the cycle time of Processor B be in order to give the same CPU time as Processor A?

9. (6 pts) In MIPS, the jump instruction uses the distance (or Immediate) field to indicate the distance from the current PC that it wants to jump.

   (2) What is that distance measured in?

   (2) How is this accomplished?

   (2) What must be done if you need to jump further than that distance?
10. (6 pts) What are the 4 benchmark types we discussed in class? Do benchmark programs remain valid indefinitely? Why or why not?

11. (3 pts) Why are there multiple dies per wafer? Why not make just one big one?

12. (4 pts) Machines used to use absolute addressing for jumps and branches. What do they use now, and why?

13. (4 pts) Interrupts/Exceptions require the CPU to provide the OS with what 2 things?

14. (2 pts) What does EPC stand for? What value does it contain?
In this question, we are going to wire up a 14-bit version of the machine we designed in class.

The machine has 3 different instruction formats: R, I, and J.

R-type:
 Opcode        rs   rt   rd   funct
 13-10  9-8   7-6   5-4   3-0

I-type:
 Opcode        rs   rt   Immediate
 13-10  9-8   7-6   5-0

J-type:
 Opcode         Offset
 13-10  9-0

The machine is word-addressable, where a word is 14 bits. Immediates are sign-extended, and in a jump instruction, the jump is not relative to the current PC, but rather is treated as an absolute value.

Here are some of the instructions that have been defined:

<table>
<thead>
<tr>
<th>Name</th>
<th>Opcode(Funct)</th>
<th>Name</th>
<th>Opcode(Funct)</th>
<th>Name</th>
<th>Opcode(Funct)</th>
</tr>
</thead>
<tbody>
<tr>
<td>lw</td>
<td>0010(XXXX)</td>
<td>sw</td>
<td>0011(XXXX)</td>
<td>NOP</td>
<td>0000(0000)</td>
</tr>
<tr>
<td>beqz</td>
<td>0100(XXXX)</td>
<td>j</td>
<td>0101(XXXX)</td>
<td>NOT</td>
<td>1000(0011)</td>
</tr>
<tr>
<td>ADD</td>
<td>1000(0000)</td>
<td>ADD Imm</td>
<td>1001(XXXX)</td>
<td>SUB</td>
<td>1000(0100)</td>
</tr>
<tr>
<td>AND</td>
<td>1000(0001)</td>
<td>AND Imm</td>
<td>1010(XXXX)</td>
<td>XOR</td>
<td>1000(0101)</td>
</tr>
<tr>
<td>OR</td>
<td>1000(0010)</td>
<td>OR Imm</td>
<td>1011(XXXX)</td>
<td>XOR Imm</td>
<td>1100(XXXX)</td>
</tr>
</tbody>
</table>

Here are the 10 control signals.

A) ALU0       B) ALU1       C) ALUSrc       D) Br       E) MemRead
F) MemWrite   G) PCin       H) RegWrite    I) WrAddr    J) WrSrc
15. (16) In the diagram below, make sure all the dashed boxes are filled. Two are already done for you. Use the letters from the previous page instead of the actual names (F instead of MemWrite, for example).

(2 pts) Now, write down the exact boolean equation for the MemWrite signal.

16. (6 pts) We need a JAL instruction - let’s say it uses register 0. Sketch the changes necessary on the above diagram, and/or describe in words what would need to change in this machine in order to make this work. (Don’t forget about instruction set impacts ...)

17. (10 pts) This 14-bit machine is very similar to the MIPS design in the book. List 5 significant differences between the two designs (and obvious, trivial things like "one is 32 bits and one is 12" don’t count.)

18. (11 pts) There are a number of changes that must be made to our single cycle design in order to make it a multicycle CPU. What are the 5 new registers that must be added, and where do they go? (Sketch them in on the diagram below). Also, there are several new control signals - list 3 of them, and explain what they do.
19. (4 pts) We are going to use microcode to provide the control signals for this multicycle CPU. We will say there are 13 control signals, and we are going to have the longest instruction take 5 cycles. Describe the simplest microcode configuration that can be used in this machine (how many entries, how wide is each entry, what does each entry contain, etc.)

1. (1) How many entries would it have?

2. (1) How wide would each entry be?

3. (1) What would be contained in each memory location?

4. (1) How would the memory locations be accessed? (In other words, what signals would you use to create the memory address?)